Precise and Efficient FIFO-Replacement Analysis Based on Static Phase Detection

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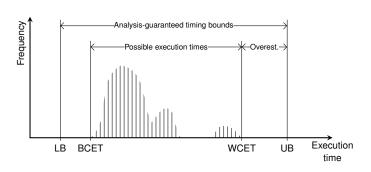
Outline



- 1 Introduction and Problem
 - Timing Analysis
 - Cache Analysis
 - Challenge FIFO Replacement
- 2 Predicting Hits for FIFO
 - Idea and Theorem
 - Must Analysis
 - Efficient Implementation
- 3 Paper Contents
- 4 Evaluation
 - Related Work
 - Analysis Precision
- 5 Summary

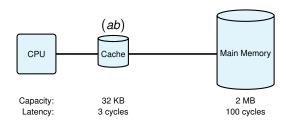
Timing Analysis for Real-Time Systems



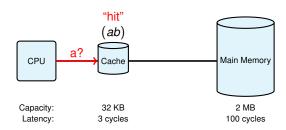


- Need to bound execution time of programs
- Execution time influenced by architectural features
 - pipelines, caches, branch prediction, . . .
- Need to analyze behavior of architectural components

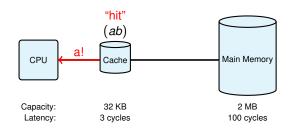




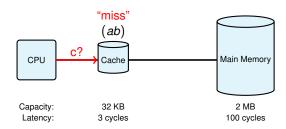




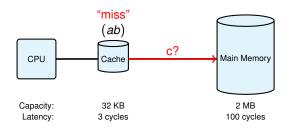




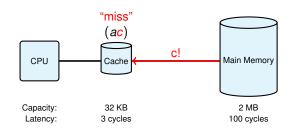












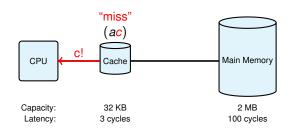
- Caches transparently buffer memory blocks
- Replacement policy dynamically decides which element to replace

LRU least recently used

PLRU pseudo LRU

FIFO first-in first-out





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- Replacement policy dynamically decides which element to replace

LRU least recently used

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Goals & Notions

- Derive approximations to cache contents at each program point
- in order to classify memory accesses as cache hits or cache misses

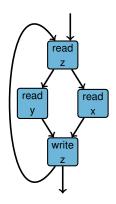
Must-information

- Underapproximation of cache contents
- Used to soundly classify cache hits

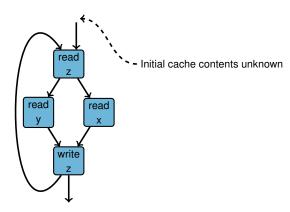
May-information

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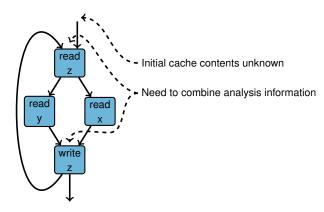
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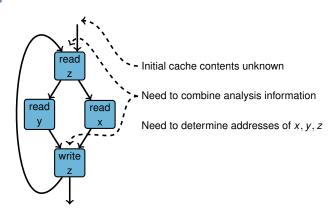
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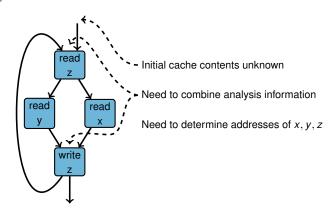
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- Approximate accessed addresses by value analysis (not this talk)
- Approximate cached contents by replacement analysis
- \Rightarrow Cache analysis = value analysis \oplus replacement analysis

FIFO Replacement



■ FIFO cache of size k:

last-in first-in
$$[\overset{\downarrow}{b_1},\ldots,\overset{\downarrow}{b_k}]\in\mathcal{Q}_k:=\mathcal{B}_{\perp}^k$$

■ Example updates:

$$[d, c, b, a] \xrightarrow{c} [d, c, b, a]$$

$$[d, c, b, a] \xrightarrow{e} [e, d, c, b]$$

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Why Predicting Hits is Difficult

- Take a set of blocks B that does fit into a cache q
- For example, $B = \{a, b, e\}$ and k = 4. $|B| \le k$.
- Access all blocks in B:

$$q \xrightarrow{\langle a,b,e \rangle} q'$$

■ Must all accessed blocks be cached? $\forall q : B \subseteq q'$?

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Why Predicting Hits is Difficult

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- Access all blocks in B:

$$q \xrightarrow{\langle a,b,e \rangle} q'$$

■ Must all accessed blocks be cached? $\forall q : B \subseteq q'$? No.

$$[d, c, b, a] \xrightarrow{a \atop hit} [d, c, b, a] \xrightarrow{b} [d, c, b, a] \xrightarrow{e \atop miss'} [e, d, c, b] \not\ni a$$

Observation

After accessing a set of "fitting" blocks, not all of them must be cached.

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Why Predicting Misses is Difficult

- Take a set of blocks B that does not fit into a cache q
- For example, $B = \{a, b, c, d, e, f\}$ and k = 4. $|B| \ge k$.
- Access all blocks in B:

$$q \xrightarrow{\langle a,b,c,d,e,f \rangle} q'$$

■ Must all non-accessed blocks be evicted? $\forall q: q' \subseteq B$?

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Why Predicting Misses is Difficult

- Take a set of blocks B that does not fit into a cache q
- For example, $B = \{a, b, c, d, e, f\}$ and k = 4. $|B| \ge k$.
- Access all blocks in B:

$$q \xrightarrow{\langle a,b,c,d,e,f \rangle} q'$$

■ Must all non-accessed blocks be evicted? $\forall q: q' \subseteq B$? No.

$$[x, c, b, a] \xrightarrow[hits]{\langle a, b, c \rangle} [x, c, b, a] \xrightarrow[misses]{\langle d, e, f \rangle} [f, e, d, x] \ni x$$

Observation

After accessing a set of "non-fitting" blocks, other blocks may still be cached.

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To the point: Anticipation & Idea



■ Considering repeated accesses to "fitting" blocks *B* helps:

$$B = \{a, b, c\}$$

 $s = \langle a, b, b, c, b, b, a, c, c, a, b, ... \rangle$
Eventually, all blocks in B must be cached.

- Need to detect repetitions
- Partition access sequence s into phases

Definition (Phase)

A *B*-phase is an access sequence *s* such that the *set* of accessed blocks A(s) = B.

$$\langle \underline{a, b, b, b, c}, \underline{b, b, a, c}, \ldots \rangle$$
 $\langle \underline{a,b,c}$ -phase



Lemma (Single Phase)

Let s be a B-phase and $|B| \le k$.

$$\forall q \in \mathcal{Q}_k, q \stackrel{s}{\rightarrow} q'$$
:



Lemma (Single Phase)

Let *s* be a *B*-phase and $|B| \le k$.

$$\forall q \in \mathcal{Q}_k, q \xrightarrow{s} q' : B \subseteq q' \vee$$

- Either all blocks already cached:
 - ▶ $B \subseteq q \Rightarrow$ only hits in $s \Rightarrow B \subseteq q'$



Lemma (Single Phase)

Let *s* be a *B*-phase and $|B| \le k$.

$$\forall q \in \mathcal{Q}_k, q \xrightarrow{s} q': \quad B \subseteq q' \lor C_1(q') \subseteq B$$

- Either all blocks already cached:
 - ▶ $B \subseteq q \Rightarrow$ only hits in $s \Rightarrow B \subseteq q'$
- 2 Or not:
 - ▶ $B \not\subseteq q \Rightarrow$ at least one miss $s \Rightarrow C_1(q') \subseteq B$

$$[d, c, b, a] \xrightarrow{\langle a, b, e \rangle} [\underbrace{e}_{C_1(q') = \{e\} \subseteq B}, d, c, b]$$



Theorem (Multiple Phases)

Let s_i be B-phases and $|B| \le k$ and $s = s_1 \circ \ldots \circ s_j$

$$\forall q \in \mathcal{Q}_k, q \xrightarrow{s} q' : B \subseteq q' \lor C_j(q') \subseteq B$$

- For each individual phase the lemma applies
- 2 Misses, if any, accumulate in last-in positions $C_j(q')$

$$[d,c,b,a] \xrightarrow{\langle a,b,e \rangle} [\underbrace{e}_{C_1 \subseteq B},d,c,b] \xrightarrow{\langle b,a,e \rangle} [\underbrace{a,e}_{C_2 \subseteq B},d,c] \xrightarrow{\langle a,b,e \rangle} [\underbrace{b,a,e}_{C_3 \subseteq B},d]$$



Theorem (Multiple Phases)

Let s_i be B-phases and $|B| \le k$ and $s = s_1 \circ \ldots \circ s_j$

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$$[d,c,b,a] \xrightarrow{\langle a,b,e \rangle} [\underbrace{e}_{C_1 \subseteq B},d,c,b] \xrightarrow{\langle b,a,e \rangle} [\underbrace{a,e}_{C_2 \subseteq B},d,c] \xrightarrow{\langle a,b,e \rangle} [\underbrace{b,a,e}_{C_3 \subseteq B},d]$$

■ Corollary: After |B| B-phases, all blocks in B must be cached

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How to Count Phases

- For phase blocks *B*, the analysis maintains:
 - *P* phase progress, blocks already accessed in current phase *pc* phase counter, number of detected *B*-phases
- lacksquare Predicts hits for blocks in B if pc = |B|

Example for $B = \{a, b\}$										
s		а	b		b	b	а		b	
Р	Ø	{a}	{a,b}	Ø	{b}	{b}	{a,b}	Ø	{b}	
<i>pc</i> Hit	0	0	0	1	1	1	1	2	2 Hit	

Dependency on Future Accesses



- Need |B| B-phases to predict hits for blocks in B
- How to choose *B*?
- After observing $\langle a, b, c \rangle$ it makes sense trying to detect
 - ▶ 2 further {a, b, c}-phases
 - ▶ 1 further {b, c}-phase
 - ▶ 0 further {c}-phases
- Optimal B depends on future accesses

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Resolving the Dependency

- Perform multiple analyses for different B sets
- For which?
- |B| already determines sensible contents of B
- For |B| = 2, after $\langle a, b, c \rangle$
 - ▶ already detected 1 {b, c}-phase
 - ▶ no advantage in trying to detect 2 $\{x, y\}$ -phases
- \Rightarrow Perform k analyses for different B sets
 - for each phase size $n = 1 \dots k$
 - ▶ *B_n* consists of the *n* most-recently-used blocks

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Subanalyses for $n = 1 \dots 3$

a b c c b c a a c a b a

n = 1:

n=2:

n=3:

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$$a \ b \ c$$
 $R = 1 :$ $R = 2 :$ $R = 3 :$

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$$a \ b \ c \ c \ b \ d \ H$$
 $n=1:$
 $n=2:$
 $n=3:$

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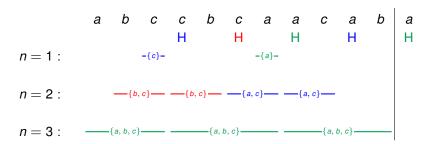
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$$a \ b \ c \ c \ b \ c \ a \ a \ c \ a \ b \ a$$
 $H \ H \ H \ H$
 $n=1:$
 $-\{c\} -\{b,c\} -\{a,c\} n=3:$

The Must Analysis

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Subanalyses for $n = 1 \dots 3$



Efficient Implementation

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Observation

- For $n = 1 \dots k$, analysis needs to maintain:
 - ▶ phase blocks $B_n \in 2^{\mathcal{B}}$
 - ▶ phase progress $P_n \in 2^{\mathcal{B}}$
 - ▶ phase counter $pc_n \in \mathbb{N}$
- Phase blocks B_n are the n most-recently-used blocks
- \Rightarrow For $i < j : B_i \subseteq B_j$
- \Rightarrow Encode all B_n in a single LRU-stack
 - For all $i : P_i \subseteq B_i$
- \Rightarrow Encode all P_n as "pointers" into the stack

Efficient Implementation

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Encoding

- For phase blocks B_n :
 - ▶ pcn complete Bn-phases were detected
 - current phase progress is B_{pp_n}

B_1	$\textit{pc}_1, \textit{pp}_1$			
$B_2 \setminus B_1$	pc_2, pp_2			
$B_3 \setminus B_2$	pc_3, pp_3			
$B_4 \setminus B_3$	pc_1, pp_1 pc_2, pp_2 pc_3, pp_3 pc_4, pp_4			

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Contents of the Paper



- So far, we have seen parts of the must-analysis
- The paper contains, for must- and may-analysis,
 - basic theorem
 - generalization to arbitrary control-flow
 - formalization as abstract interpretation

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Brief History of Replacement Analysis



Before '97 LRU analyses

LCTRTS'97 Precise and efficient must- and may-analysis for LRU [1]

LCTES'08 Generic analyses for FIFO and PLRU [2]

SAS'09 Cache analysis framework and FIFO analysis [3]

WCET'10 Toward precise analysis for PLRU [4]

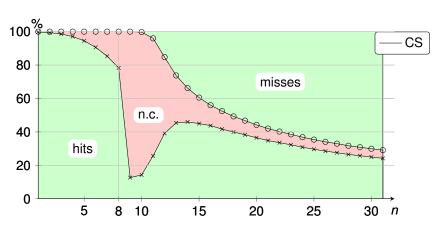
ECRTS'10 Precise and efficient must- and may-analysis for FIFO

Evaluation Setup



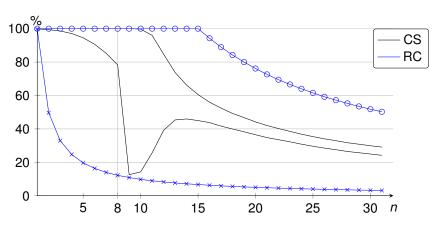
- Analyses:
 - HAM Must-analysis of SAS'09
 - RC Generic analyses of LCTES'08
 - PD Phase detecting analyses
- Collecting semantics:
 - CS Limit for any static analysis
- Spectrum of synthetic benchmarks:
 - Random access sequences and program fragments
 - With varying locality

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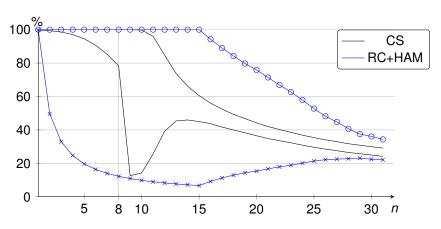
- n is number of distinct elements that get accessed
- Average guaranteed hit- and miss-rates

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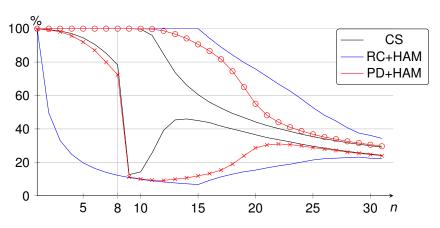
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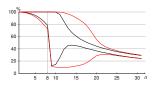
Summary



Precise and Efficient FIFO-Replacement Analysis based on Static Phase Detection

Summary





Precise and Efficient FIFO-Replacement Analysis based on Static Phase Detection

- Two theorems on FIFO-contents
 - bound on number of phases
 - must be cached / evicted

- Must- and may-analysis
 - static phase detection
 - multiple sub-analyses

Further Reading





C. Ferdinand

Cache Behaviour Prediction for Real-Time Systems PhD Thesis, Saarland University, 1997



J. Reineke and D. Grund

Relative competitive analysis of cache replacement policies LCTES 2008



D. Grund and J. Reineke

Abstract Interpretation of FIFO Replacement SAS 2009



D. Grund and J. Reineke

Toward Precise PLRU Cache Analysis

WCET 2010

Related Work: LRU Analyses



Analyses directed at worst-case execution-time analysis

Mueller By "static cache simulation"

Li By integer linear programming
Ferdinand By abstract interpretation

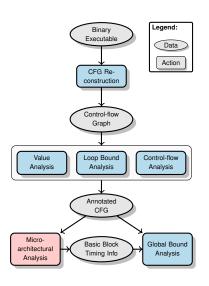
Other than that

Ghosh Cache Miss Equations, loop nests
Chatterjee Exact model of cache behavior for loop nests

All for LRU caches only

Static Timing-Analysis Framework





Micro-architectural analysis

- models pipeline, caches, buses, etc.
- derives bounds on BB exec. times
- is an abstract interpretation with a huge domain
- is the computationally most expensive module

Applicability



- Any buffer with transparent FIFO replacement:
 - Individual cache sets of instruction of data caches (I\$, D\$)
 - Branch target buffers (BTB, BTIC)
 - Translation lookaside buffers (TLB)
- Instances:

```
I$ D$ ARM 1136, 1156, 1176, 920T, 922T, 926EJ-S (k \in \{2, 4, 64\})
```

I\$ D\$ Marvell (Intel) XScale(s) (k = 32)

BTB Freescale (Motorola) MPC 56x, 7450-Family ($k \in \{4, 8\}$)

. . .

Must Analysis

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Full Example for k = 3

■ For $1 \le n \le k$ maintain B_n, P_n, pc_n

Example									
s		а	b	С	С	b	С	а	
B ₁	Ø	{a}	{b}	{c}	{c}	{b}	{c}	{a}	
P_1	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	
pc_1	0	1	1	1	1	1	1	1	
B_2	Ø	{a}	{a,b}	{b, c}	{b, c}	{b, c}	{b, c}	{a, c}	
P_2	Ø	{a}	Ø	Ø	{ c }	Ø	{ c }	Ø	
pc_2	0	0	1	1	1	2	2	1	
B_3	Ø	{a}	{a,b}	{a, b, c}	{a, b, c}	{a, b, c}	{a,b,c}	$\{a,b,c\}$	
P_3	Ø	{ <i>a</i> }	$\{a,b\}$	Ø	{ <i>c</i> }	$\{m{b},m{c}\}$	$\{m{b},m{c}\}$	Ø	
pc_3	0	0	0	1	1	1	1	2	
Hit					Hit		Hit		

Must Analysis

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Abstraction and Join

- Analysis domain is $Lru_k^{\leq} \times PC_k \times PP_k \subset (2^{\mathcal{B}})^k \times \mathbb{N}^k \times \mathbb{N}^k$ Lru_k^{\leq} LRU must-analysis, under-approximates accessed blocks PC_k lower bounds on number of phases PP_k lower bounds on phase progress
- Reuse abstract transformer and join of Lru_k^{\leq}
- Define appropriately for PC_k and PP_k

May-Analysis



- Similar to must-analysis
- Difference: Phases may be of different lengths and contents

Theorem (Multiple Phases)

$$s = s_1 \circ \ldots \circ s_j, \forall i : |A(s_i)| = n_i \ge k:$$

$$\forall q \in \mathcal{Q}_k, q \xrightarrow{s} q' : \quad C_{\sum_{i=1}^j (n_i - k + 1)}(q') \subseteq A(s) = \bigcup_i A(s_i)$$

- More simultaneous sub-analyses
- Similar implementation employing LRU may-analysis